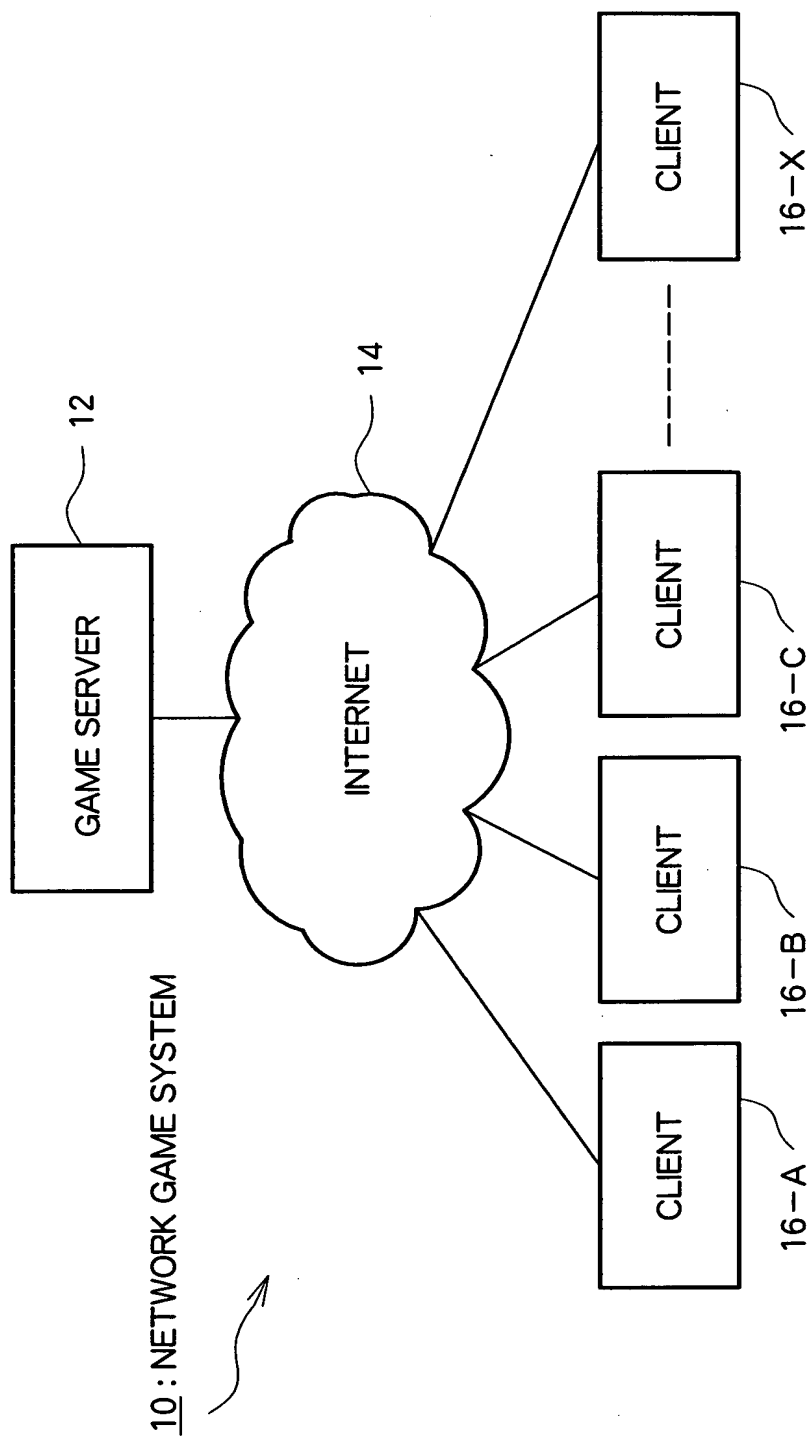


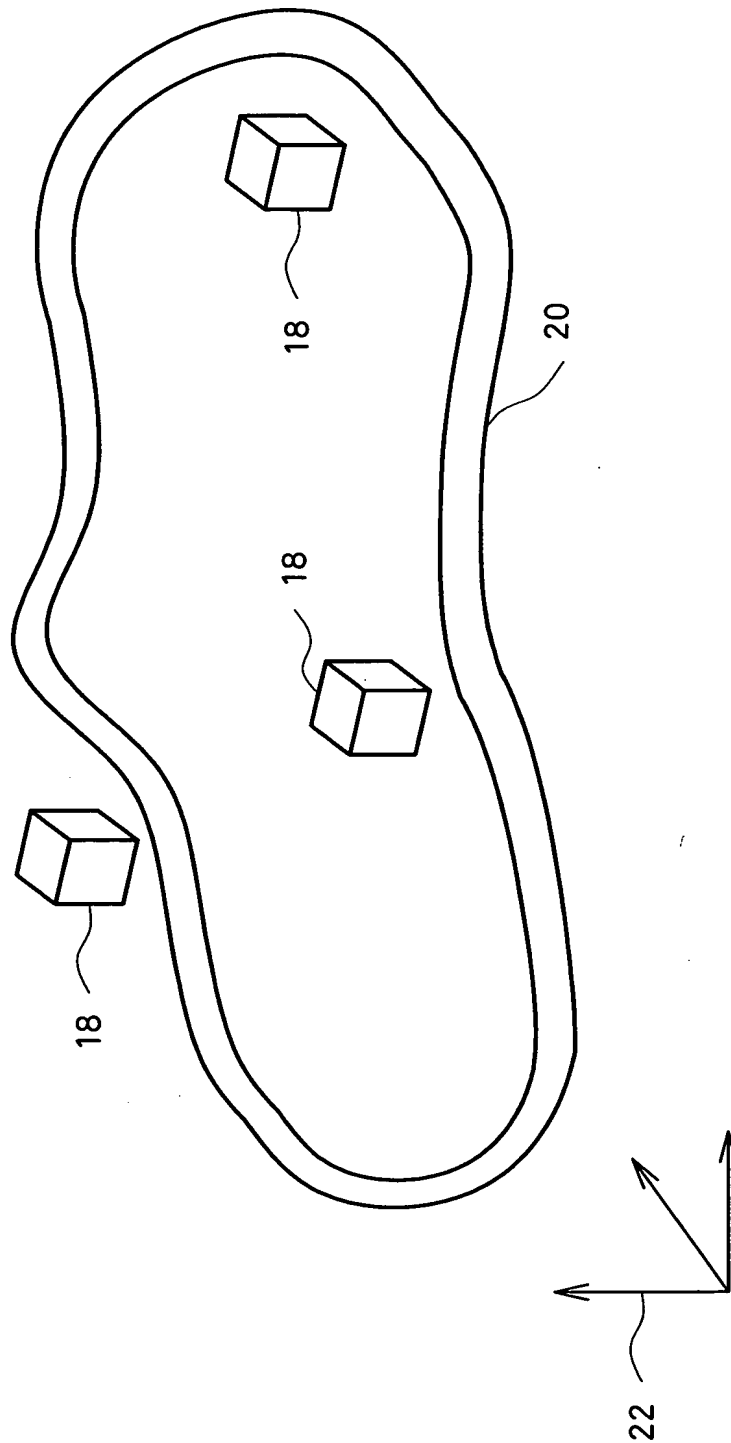
1 / 1 1

FIG. 1



2 / 1 1

FIG. 2



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FIG. 3

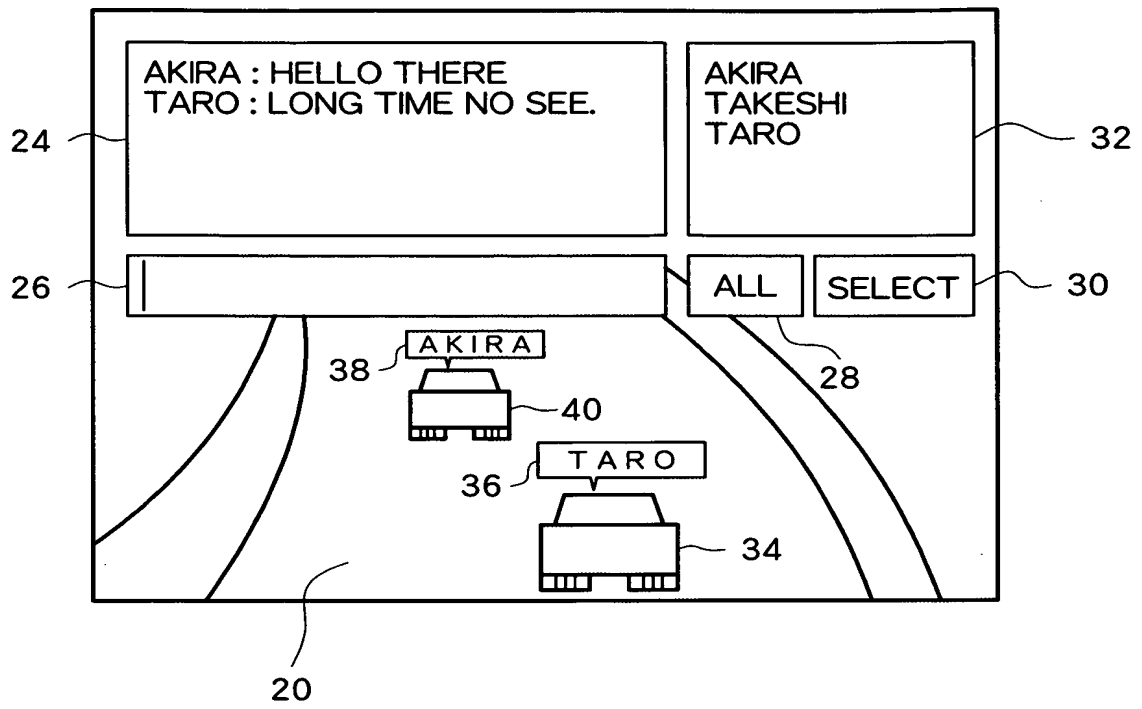
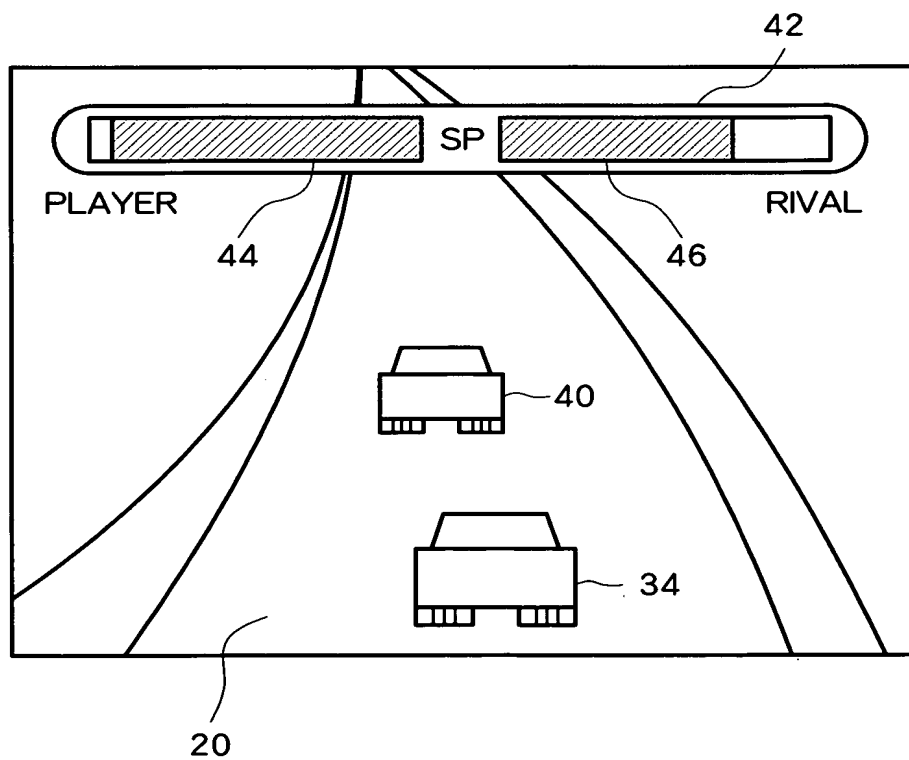
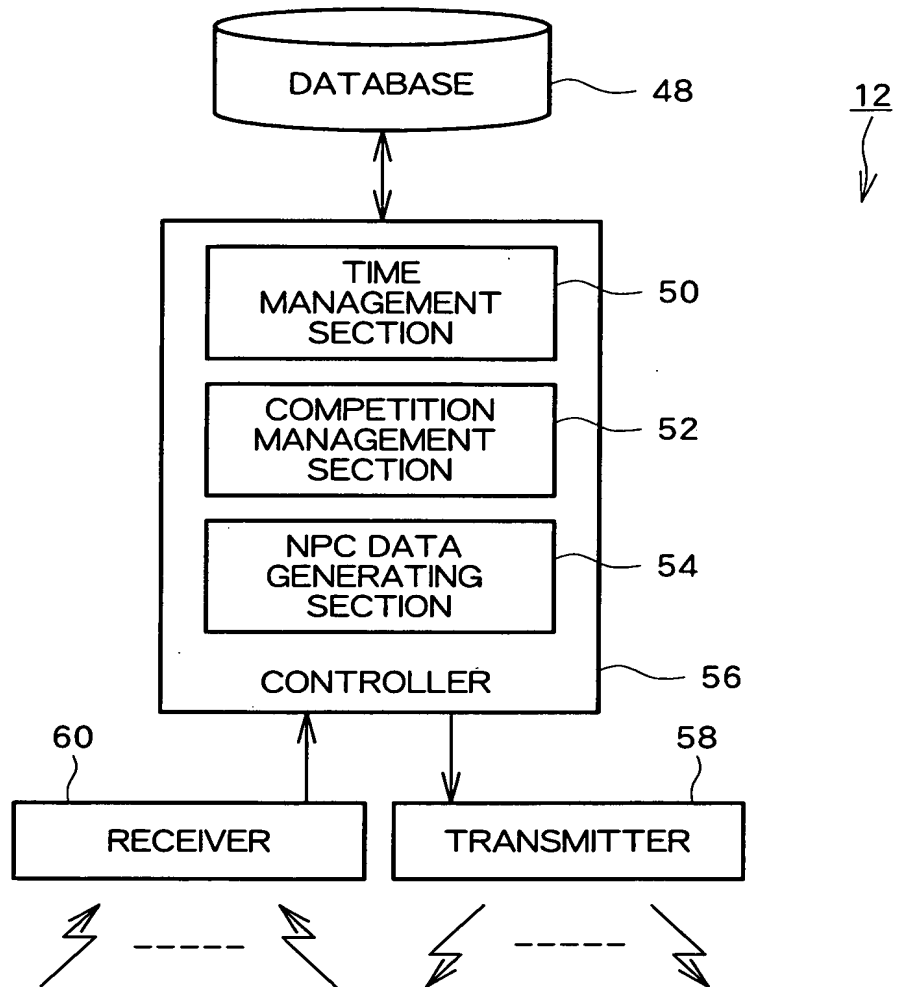


FIG. 4



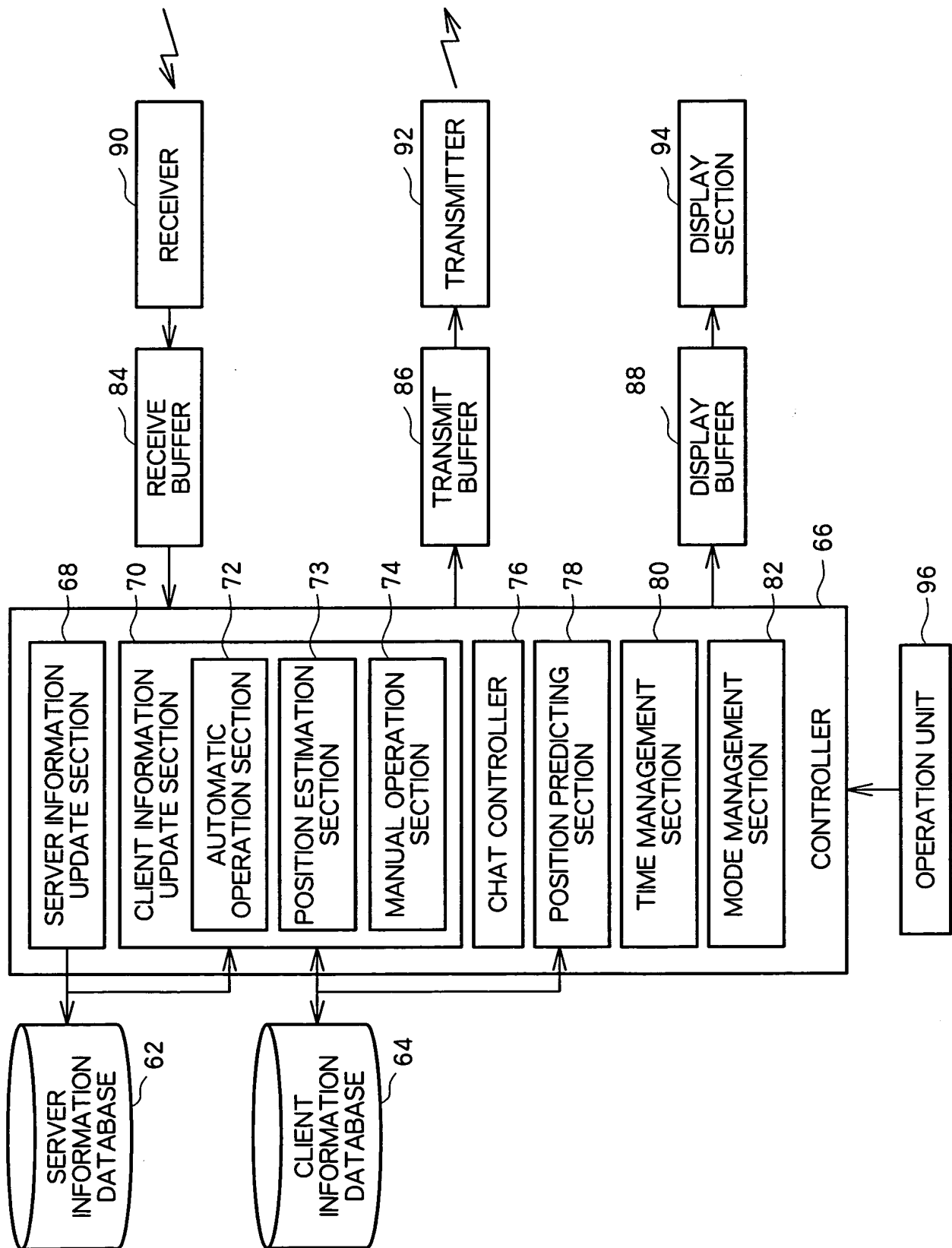
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FIG. 5



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FIG. 6



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FIG. 7

| I D | LATEST CURRENT POSITION/TIME | LATEST PREDICTED FUTURE POSITION/TIME | COMPETING FLAG |
|---------|---------------------------------|--|-------------------|
| KEN | PA (KEN) / T (KEN) | PE (KEN) / T (KEN)+ α | 1 |
| TARO | PA (TARO) / T (TARO) | PE (TARO) / T (TARO)+ α | 1 |
| TAKESHI | PA (TAKESHI) / T (TAKESHI) | PE (TAKESHI) / T (TAKESHI)+ α | 0 |
| SNPC1 | PA (SNPC1) / T (SNPC1) | PE (SNPC1) / T (SNPC1)+ α | 0 |

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FIG. 8

| I D | ADDRESS |
|-------|----------------------------|
| AKIRA | x x x. x x x. x x x. x x x |
| TARO | x x x. x x x. x x x. x x x |
| KEN | x x x. x x x. x x x. x x x |

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FIG. 9

| I D | LATEST CURRENT POSITION/TIME | LATEST PREDICTED FUTURE POSITION/TIME |
|-----------|---------------------------------|---|
| KEN | PA (KEN) / T (KEN) | PE (KEN) / T (KEN) + α |
| TARO | PA (TARO) / T (TARO) | PE (TARO) / T (TARO) + α |
| CNPCKEN1 | PA (CNPCKEN1) / T (CNPCKEN1) | PE (CNPCKEN1) / T (CNPCKEN1) + α |
| CNPCTARO1 | PA (CNPCTARO1) / T (CNPCTARO1) | PE (CNPCTARO1) / T (CNPCTARO1) + α |

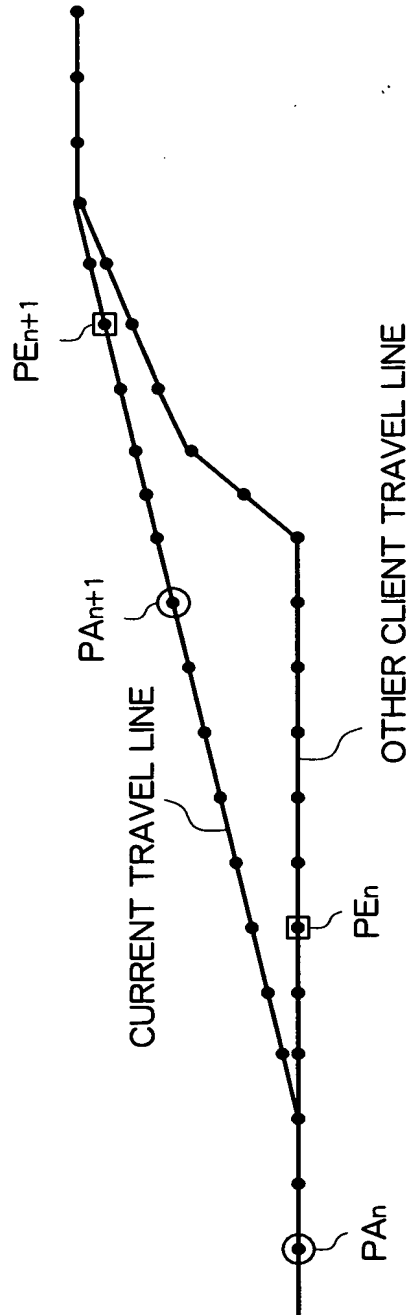
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FIG.10

| I D | CURRENT POSITION | CURRENT ATTITUDE | CURRENT SPEED VECTOR |
|---------|---------------------|---------------------|-------------------------|
| KEN | PA (KEN) | BA (KEN) | VA (KEN) |
| TARO | PA (TARO) | BA (TARO) | VA (TARO) |
| TAKESHI | PA (TAKESHI) | BA (TAKESHI) | VA (TAKESHI) |
| SNPC1 | PA (SNPC1) | BA (SNPC1) | VA (SNPC1) |

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FIG. 11



1 1 / 1 1

FIG. 12

